

# Autonics ROTARY ENCODER (INCREMENTAL TYPE) E60H SERIES INSTRUCTION MANUAL



Thank you for choosing our Autonics product.  
Please read the following safety considerations before use.

## ■ Safety Considerations

※ Please observe all safety considerations for safe and proper product operation to avoid hazards.  
※ ⚠ symbol represents caution due to special circumstances in which hazards may occur.

- ⚠ **Warning** Failure to follow these instructions may result in serious injury or death.
- ⚠ **Caution** Failure to follow these instructions may result in personal injury or product damage.

## ⚠ Warning

- Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.** (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)  
Failure to follow this instruction may result in fire, personal injury, or economic loss.
- Install on a device panel to use.**  
Failure to follow this instruction may result in fire.
- Do not connect, repair, or inspect the unit while connected to a power source.**  
Failure to follow this instruction may result in fire.
- Check 'Connections' before wiring.**  
Failure to follow this instruction may result in fire.
- Do not disassemble or modify the unit.**  
Failure to follow this instruction may result in fire.

## ⚠ Caution

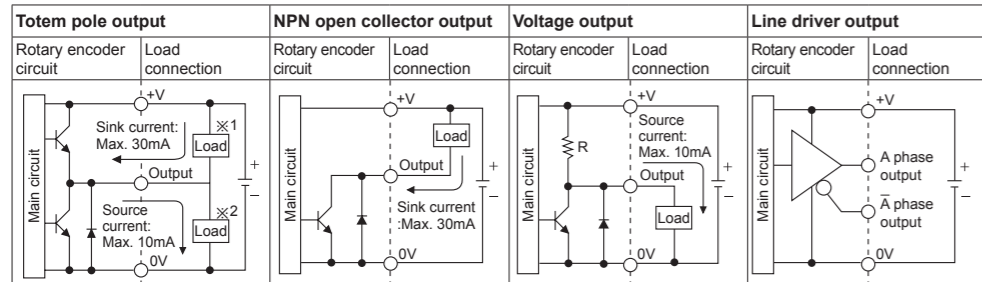
- Use the unit within the rated specifications.**  
Failure to follow this instruction may result in fire or product damage.
- Do not short the load.**  
Failure to follow this instruction may result in product damage by fire.
- Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present.**  
Failure to follow this instruction may result in fire or explosion.
- Do not use the unit near the place where there is the equipment which generates strong magnetic force or high frequency noise and strong alkaline, strong acidic exists.**  
Failure to follow this instruction may result in product damage.

## ■ Ordering Information

<b>E60H</b>	<b>20</b>	<b>8192</b>	<b>3</b>	<b>N</b>	<b>24</b>	
Series	Shaft inner diameter	Pulses/Revolution	Output phase	Control output	Power supply	Cable
Diameter Ø60mm, hollow shaft type	Ø20mm	100, 1024, 5000, 8192	3: A, B, Z 6: A, Ā, B, B̄, Z, Z̄	T: Totem pole output N: NPN open collector output V: Voltage output L: Line driver output	5: 5VDC ±5% 24: 12-24VDC ±5%	No mark: Radial cable type C: Radial cable connector type (※)

※ Cable length : 250mm

## ■ Control Output Diagram

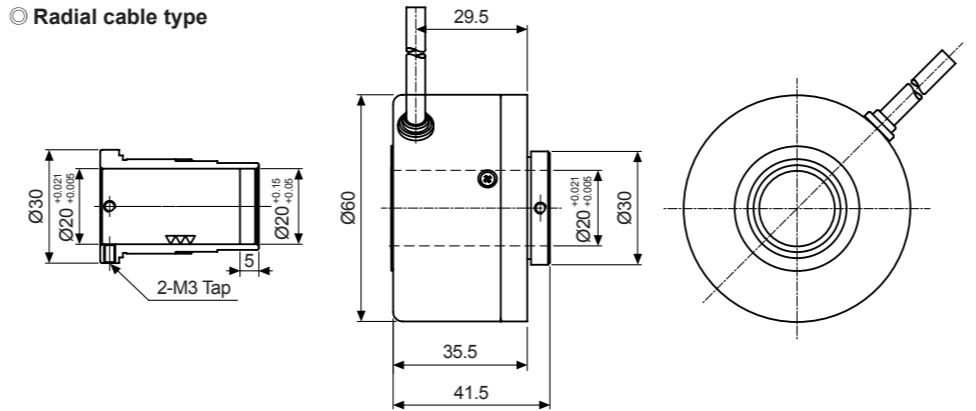


※ All output circuits of A, B, Z phase are same. (line driver output is A, Ā, B, B̄, Z, Z̄)  
 ※ Totem pole output type can be used for NPN open collector output type (※1) or voltage output type (※2).  
 ※ The above specifications are subject to change and some models may be discontinued without notice.  
 ※ Be sure to follow cautions written in the instruction manual, and the technical descriptions (catalog, homepage).

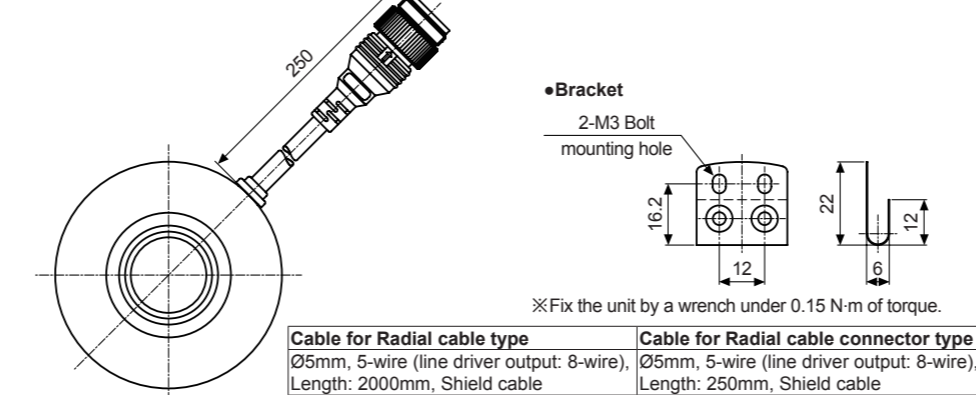
## ■ Specifications

Item	Diameter Ø60mm hollow shaft type of incremental rotary encoder		
Model	Totem pole output	E60H20-□-3-T-□	
	NPN open collector output	E60H20-□-3-N-□	
	Voltage output	E60H20-□-3-V-□	
	Line driver output	E60H20-□-6-L-□	
Resolution (PPR) <sup>※1</sup>	100, 1024, 5000, 8192		
Output phase	A, B, Z phase (line driver output: A, Ā, B, B̄, Z, Z̄ phase)		
Phase difference of output	Phase difference between A and B: $\frac{T}{4} \pm \frac{T}{8}$ (T=1 cycle of A phase)		
Electrical specification	Totem pole output	•[Low] - Load current: Max. 30mA, Residual voltage: Max. 0.4VDC= •[High] - Load current: Max. 10mA, Output voltage (power voltage 5VDC=): Min. (power voltage-2.0)VDC= Output voltage (power voltage 12-24VDC=): Min. (power voltage-3.0)VDC=	
	NPN open collector output	Load current: Max. 30mA, Residual voltage: Max. 0.4VDC=	
	Voltage output	Load current: Max. 10mA, Residual voltage: Max. 0.4VDC=	
	Line driver output	•[Low] - Load current: Max. 20mA, Residual voltage: Max. 0.5VDC= •[High] - Load current: Max. -20mA, Output voltage (power voltage 5VDC=): Min. 2.5VDC= Output voltage (power voltage 12-24VDC=): Min. (power voltage-3.0)VDC=	
Response time (rise / fall)	Totem pole output	Max. 1µs (cable length: 2m, I sink = 20mA)	
	NPN open collector output		
	Voltage output		
	Line driver output		
Max. Response frequency	300kHz		
Power supply	•5VDC= ±5% (ripple P-P: Max. 5%)      •12-24VDC= ±5% (ripple P-P: Max. 5%)		
Current consumption	Max. 80mA (disconnection of the load), Line driver output: Max. 50mA (disconnection of the load)		
Insulation resistance	Over. 100MΩ (at 500VDC megger between all terminals and case)		
Dielectric strength	750VAC 50/60Hz for 1 minute (between all terminals and case)		
Connection	Radial cable type, Radial cable connector type		
Mechanical specification	Starting torque	Max. 150gf·cm (0.0147 N·m)	
	Moment of inertia	Max. 110g·cm <sup>2</sup> (11×10 <sup>-6</sup> kg·m <sup>2</sup> )	
	Shaft loading	Radial: 5kgf, Thrust: 2.5kgf	
	Max. allowable revolution <sup>※2</sup>	6,000rpm	
Vibration	1.5mm amplitude at frequency of 10 to 55Hz (for 1 min.) in each X, Y, Z direction for 2 hours		
Shock	Approx. Max. 100G		
Environment	Ambient temperature	-10 to 70°C, Storage: -25 to 85°C	
	Ambient humidity	35 to 85%RH, Storage: 35 to 90%RH	
Protection structure	IP50 (IEC standards)		
Cable	Ø5mm, 5-wire, Length: 2m, Shield cable (line driver output: Ø5mm, 8-wire) (AWG24, Core diameter: 0.08mm, Number of cores: 40, Insulator out diameter: Ø1mm)		
Accessory	Bracket: 2		
Approval	CE (except line driver output)		
Weight <sup>※3</sup>	Approx. 397g (approx. 330g)		

## ■ Dimensions



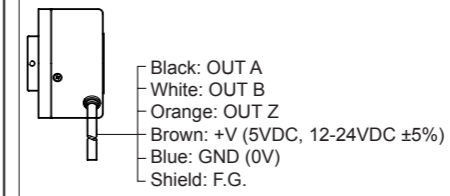
## ⊙ Radial cable connector type



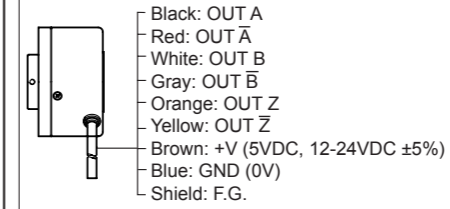
## ■ Connections

### ⊙ Radial cable type

- Totem pole output
- NPN open collector output
- Voltage output



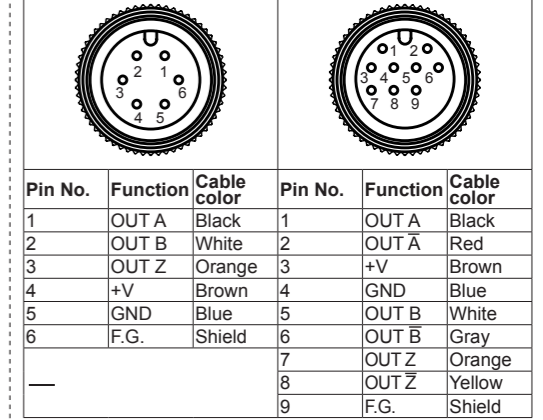
### • Line driver output



- ※ Unused wires must be insulated.
- ※ The metal case and shield cable of encoder should be grounded (F.G.).
- ※ Do not apply tensile strength over 30N to the cable.

### ⊙ Radial cable connector type

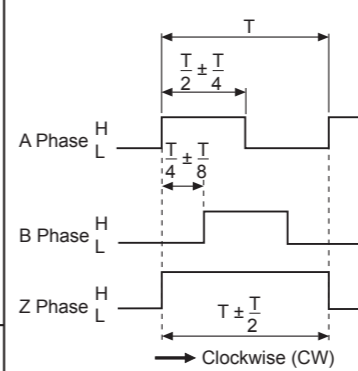
- Totem pole output
- NPN open collector output
- Voltage output
- Line driver output



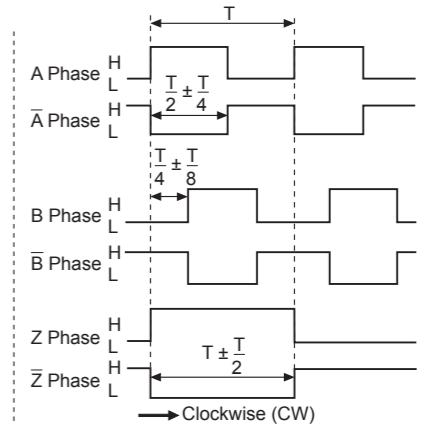
※ F.G. (Field Ground): It should be grounded separately.

## ■ Output Waveforms

- Totem pole output / NPN open collector output / Voltage output



- Line driver output



## ■ Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.
- 5VDC, 12-24VDC power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- For using the unit with the equipment which generates noise (switching regulator, inverter, servo motor, etc.), ground the shield wire to the F.G. terminal.
- Ground the shield wire to the F.G. terminal.
- When using switching mode power supply, frame ground (F.G.) terminal of power supply should be grounded.
- Wire as short as possible and keep away from high voltage lines or power lines, to prevent inductive noise.
- Check the wire type and response frequency when extending wire because of distortion of waveform or residual voltage increment etc by line resistance or capacity between lines.
- This unit may be used in the following environments.
  - ⊙ Indoors (in the environment condition rated in 'Specifications')
  - ⊙ Altitude max. 2,000m
  - ⊙ Pollution degree 2
  - ⊙ Installation category

## ■ Major Products

- Photoelectric Sensors
- Fiber Optic Sensors
- Door Sensors
- Door Side Sensors
- Area Sensors
- Proximity Sensors
- Pressure Sensors
- Rotary Encoders
- Connector/Sockets
- Switching Mod. Pure Steps
- Control Switches
- I/O Terminal Blocks & Cables
- Stepper Motors/Drivers/Motion Controllers
- Graphic/Logic Panels
- Field Network Devices
- Laser Marking System (Fiber, Co<sub>2</sub>, Nd:YAG)
- Laser Welding/Cutting System
- Temperature Controllers
- Humidity/Humidity Transducers
- SSR/Power Controllers
- Counters
- Timers
- Panel Meters
- Tachometer/Pulse (Rate) Meters
- Display Units
- Sensor Controllers

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021 6639 39 00  
0912 147 3023

ali5.ir

**Autonics Corporation**  
http://www.autonics.com

HEADQUARTERS:  
18, Bansong-ro 513 beon-gil, Haeundae-gu, Busan, South Korea, 48002  
TEL: 82-51-519-3232  
E-mail: sales@autonics.com