

## NON-CONTACT INCREMENTAL ROTARY ENCODER



ARP T 50 series rotary encoders measure with magnetic principle and work contactless.

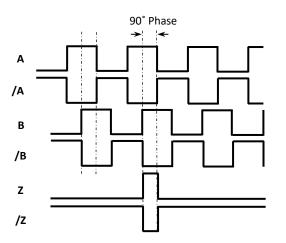
They consist of 2 parts, the encoder body and magnet. They have long operating life as they make noncontact measurement. They can also operate at high speeds up to 20,000 RPM. They work incrementally and offer resolution up to 1024 pulses.

Standard IP54, optionally IP67 protection class is available.

MECHANICAL DATA								
Dimensions	Encoder: Ø50							
	Rotor: Ø27							
Material	Aluminum							
<b>)</b> #/_;_ht	Encoder: ~180g							
Weight	Rotor: ~10g							
ENVIRONMENTAL DATA								
Protection Class	IP54 (Optional IP67)							
Operating Temp.	-25°C+85°C							
Storage Temp.	-40°C+100°C							
ELECTRICAL DATA								
Measuring Type	Magnetic, non-contact							
Resolution	All resolution values between 1 and 1024 pulses							
Operating Speed	20.000 RPM max.							
Response Frequency	300 KHz							
<b>Current Consumption</b>	50 mA nominal							
		PP	TTL	HTL	HPL	OCL	ОСР	
Supply and Output Type	Supply	1030 VDC	5 VDC	1030 VDC	530 VDC	The supply signal lower than the ou		
	Output	1030 VDC PP	5 VDC TTL	5 VDC TTL	530 VDC PP	NPN Open Collector	PNP Open Collector	
Output Signals	A, /A, B, /B, Z, /Z							
Output Current	100 mA max. (per channel)							
Electrical Connection	5 x 0,14mm <sup>2</sup> shielded cable (outer dimater: $5 \pm 0,2$ mm) (When output signal is selected as 2 or 3) 8 x 0,14mm <sup>2</sup> shielded cable (outer dimater: $6,5 \pm 0,2$ mm) (When output signal is selected as 4 or 6)							

## **ELECTRICAL CONNECTION**

SIGNAL	CABLE COLOR		
А	YELLOW		
/В	WHITE		
+V	RED		
0 V	BLACK		
/A	BLUE		
В	GREEN		
/Z	GREY		
Z	PINK		



The table above shows the cable colors of the sensor output signals. If the control circuit is suitable in the Line Driver sensors of the not output signals (/A, /B, /Z) have to be added to the system. If it is not suitable /A, /B, /Z signal cables must be fixed as insulated separately. Don't forget that these edges have electricity too.

## **MECHANICAL DIMENSIONS (mm)**

